

# User Thread Implementation

COMP755

Advanced OS

*“America is not a blanket woven from one thread, one color, one cloth.”*

Jesse Jackson

# Thread Implementations

- You can implement the concept of threads at the system level or at the user level.
- The system level has several advantages:
  - Access to all the hardware and CPUs
  - Ability to respond to interrupts
  - Ability to preempt a thread

# User Threads

- This is an example of how you might implement threads at the user level.
- It is difficult to preempt a thread. Threads can voluntarily allow another thread to run.
- The `yield` method allows the thread system to consider scheduling another thread. It does not directly do anything for the calling thread.

# Example using User Threads

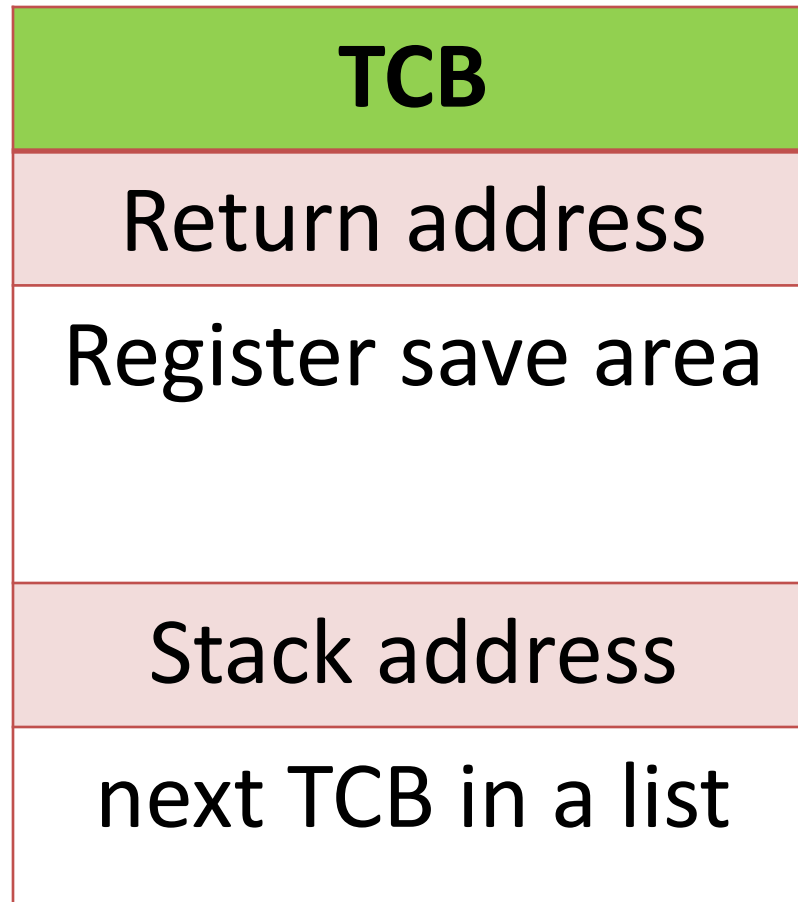
```
void main () {  
    .  
    spawn( printit );  
    .  
    do {  
        ...  
        yield( );  
        ...  
    } until whatever;  
}
```

```
void printit(void) {  
    do {  
        print a line;  
        yield( );  
    } until end of data;  
    terminate( );  
}
```

# Implementation Details

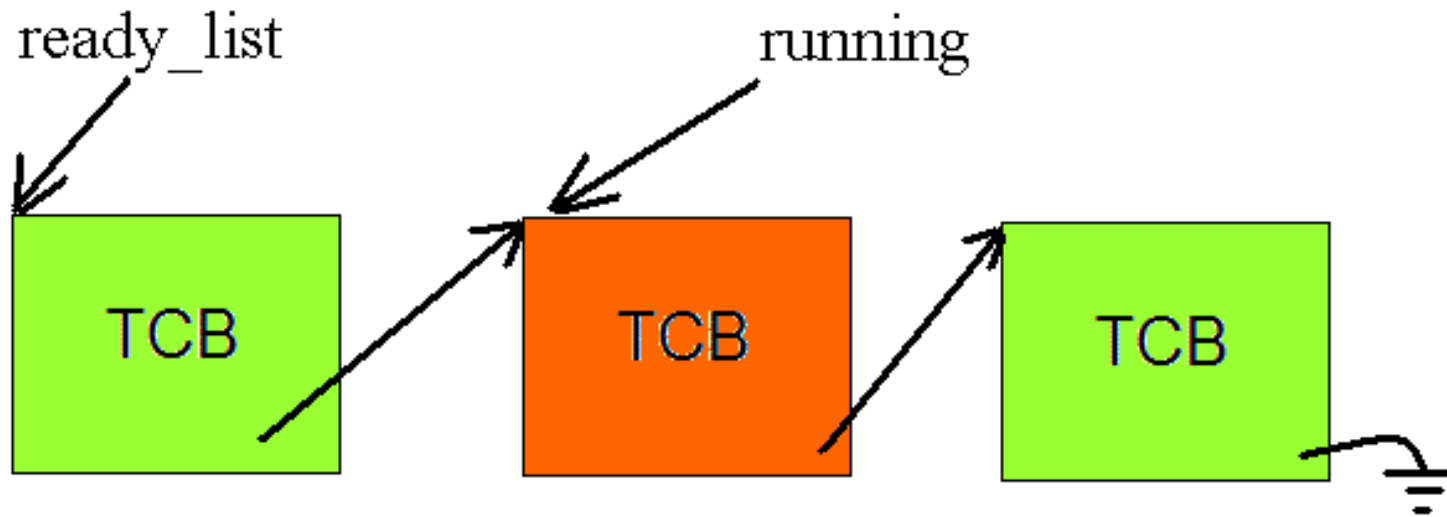
- My example thread system would probably have to be implemented in assembler.
- You have to be able to save the registers and set the stack address
- This user thread implementation does not attempt to use multiple processors

# Thread Control Block



# Thread System Data

- ready\_list – a linked list of thread control blocks
- running – the currently executing thread's TCB





# Scheduling a Thread to Run

```
private void schedule() { /* internal function */  
    Select one of the control blocks from the ready list;  
    Set running to the selected thread control block;  
    Load the registers from the save area;  
    Jump to the return address;  
}
```

- Note that the schedule function does not return to the caller in the usual sense

# Starting a New Thread

```
public void spawn(function) {
```

```
    In running thread's control block, save registers  
    and return address;
```

```
    Create a new control block;
```

```
    Copy the running thread's control block to the  
    new control block;
```

```
    Set return address to the address of the function;
```

```
    Acquire memory for a stack;
```

```
    Put the stack address in the new control block;
```

```
    Put return address of terminate() on the stack;
```

```
    Put the new control block on the ready list;
```

```
    schedule();
```

```
}
```

# Terminating a Thread

```
public void terminate() {
```

```
    Remove the current TCB from the running list;
```

```
    Release the stack memory for the running thread;
```

```
    Release the control block for the running thread;
```

```
    If no TCBs left on the ready list
```

```
        exit(); to terminate the process
```

```
    else
```

```
        schedule();
```

```
}
```

- Note that the terminate function never returns to the caller

# Giving Up Control

- Can be called by a user to allow some other thread the change to run.
- This thread might resume immediately.

```
public void yield() {
```

```
    In running thread's control block, save registers and  
    return address;
```

```
    schedule();
```

```
}
```

# Implement Semaphores

- In a group of no more than three students, write P() and V() methods to implement semaphores
- Turn your implementation in before the end of class
- Include the names of the students in your group

```
public class Semaphore {
    int counter = 0;
    public Semaphore(int initial) {
        counter = initial;
    }
    public synchronized void V() {
        counter++;
        notify();
    }
    public synchronized void P() {
        while (counter == 0) wait();
        counter--;
    }
}
```

# Semaphore Objects

```
public class Semaphore {  
    int counter;  
    TCB waiting; /* list of suspended threads */  
    public Semaphore(int initialValue) {  
        counter = initialValue;  
    }  
}
```

# Wait method

```
public void P() {  
    if (counter <= 0) {  
        save registers and return address in TCB;  
        remove TCB from ready list;  
        put TCB on waiting list;  
        schedule();  
    }  
    counter--;  
}
```



# Signal method

```
public void V() {  
    counter++;  
    if (waiting != null) {  
        Remove one TCB from waiting list;  
        put TCB on ready_list;  
        yield();  
    }  
}
```

# User and System Threads

